
UNIVERSITI SAINS MALAYSIA

Peperiksaan Semester Pertama
Sidang Akademik 2004/2005

Oktober 2004

EEE 228E – ISYARAT DAN SISTEM

Masa : 3 Jam

ARAHAN KEPADA CALON:-

Sila pastikan kertas peperiksaan ini mengandungi **SEPULUH (10)** muka surat beserta **Lampiran (10 muka surat)** bercetak dan **ENAM (6)** soalan sebelum anda memulakan peperiksaan ini.

Jawab **LIMA (5)** soalan.

Agihan markah diberikan di sut sebelah kanan soalan berkenaan.

Semua soalan hendaklah dijawab di dalam **Bahasa Malaysia** atau **Bahasa Inggeris** atau kombinasi **kedua-duanya**.

1. (a) Salah satu fungsi terpenting dalam bidang isyarat dan sistem ialah isyarat eksponen e^{st} , yang mana s adalah kompleks secara am, diberikan sebagai

One of the most important functions in the area of signals and systems is the exponential signal e^{st} , where s is complex in general, given by

$$s = \sigma + j\omega$$

Fungsi e^{st} , meliputi satu kelas besar fungsi-fungsi. Bincangkan empat kes khas e^{st} secara penuh.

The function e^{st} encompasses a large class of functions. Discuss the four special cases of e^{st} fully.

(12%)

- (b) Suatu sinusoid $e^{\sigma t} \cos \omega t$ boleh diungkapkan sebagai jumlah eksponen e^{st} dan e^{-st} . Lokasikan dalam satah frekuensi kompleks (satah-s) frekuensi-frekuensi sinusoid berikut:

A sinusoid $e^{\sigma t} \cos \omega t$ can be expressed as a sum of exponentials e^{st} and e^{-st} . Locate in the complex frequency plane (s-plane) the frequencies of the following sinusoids:

[i] $e^{-2t} \cos (5t + \theta)$

[ii] $\cos (5t + \theta)$

[iii] e^{-8t}

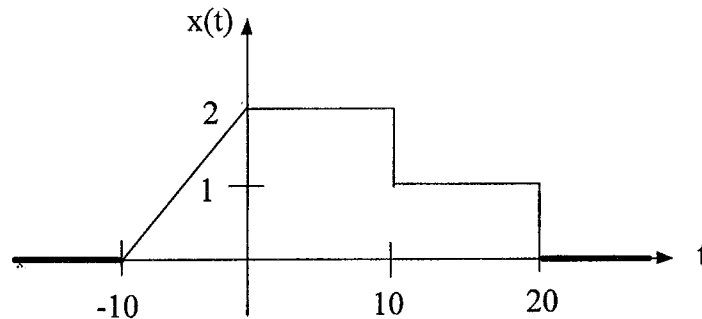
[iv] 8

(8%)

...3/-

2. (a) Pertimbangkan isyarat yang ditunjukkan dalam Rajah 1.

Consider the signal shown in Figure 1.



Rajah 1
Figure 1

- (b) Plot

[i] $x(3 + t)$

[ii] $x\left(-\frac{t}{3}\right)$

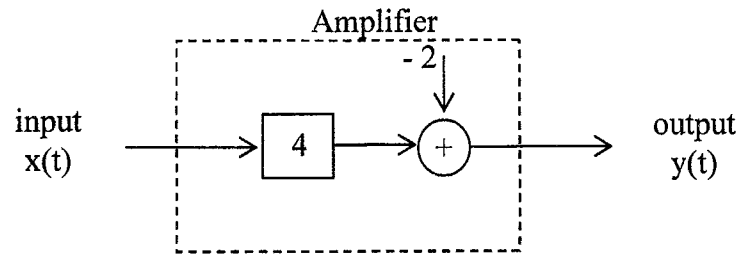
[iii] $x(2 - t)$

(10%)

- (b) Katakan isyarat $x(t)$ dalam Rajah 1 dikenakan kepada suatu penguat yang mempunyai gandaan 4 dan memperkenalkan pincangan (nilai arus terus) -2 seperti yang ditunjukkan dalam Rajah 2. Cari dan plot isyarat keluaran penguat, $y(t)$.

Suppose that the signal $x(t)$ of Figure 1 is applied to an amplifier that has a gain of 4 and introduces a bias (dc value) of -2 as shown in Figure 2. Find and plot the amplifier output signal, $y(t)$.

(10%)



Rajah 2
Figure 2

3. (a) Pertimbangkan pengkamir dalam Rajah 3. Sistem ini mempunyai sambutan dedenyut $h(t) = u(t)$. Menggunakan pengkamiran konvolusi, cari sambutan sistem kepada masukan, $x(t) = e^{5t}u(t)$. Lakarkan isyarat masukan, $x(t)$.

Consider the integrator in Figure 3. This system has the impulse response $h(t) = u(t)$. Using the convolution integral, find the system response to the input, $x(t) = e^{5t}u(t)$. Sketch the input signal, $x(t)$.



Rajah 3
Figure 3

(6%)

- (b) Diberi
Given

$$x(t) = 2[u(t) - u(t - 2)]$$

...5/-

- [i] Ungkapkan $x(t)$ dalam bentuk fungsi segiempat.

Express $x(t)$ in the form of the rectangular function.

(3%)

- [ii] Guna jadual jelmaan Fourier dan jadual operasi dalam Lampiran A, cari jelmaan Fourier untuk $x(t)$.

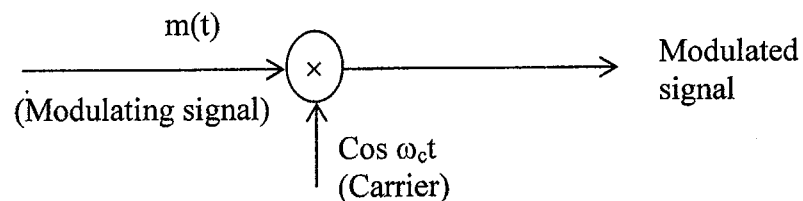
Use the table of Fourier transforms and table of operations in Appendix A, find the Fourier transform of $x(t)$.

(6%)

- (c) DSB/SC – AM dicapai dengan mendarabkan isyarat maklumat (mesej), $m(t)$ dengan suatu isyarat sinus dipanggil isyarat pembawa $\cos \omega_c t$, yang berada pada frekuensi yang dikehendaki untuk penghantaran radio secara berkesan. Proses ini ditunjukkan dalam Rajah 4(a). Untuk isyarat mesej yang ditunjukkan dalam Rajah 4(b), lakarkan isyarat termodulat.

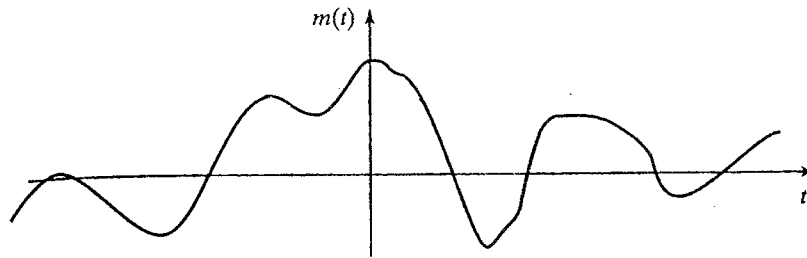
DSB/SC – AM is accomplished by multiplying the information (message) signal, $m(t)$ by a sinusoidal signal called the carrier signal $\cos \omega_c t$, which is at the desired frequency for efficient radio transmission. This process is illustrated in Figure 4(a). For the message signal shown in Figure 4(b), sketch the modulated signal.

(5%)



Rajah 4(a)
Figure 4(a)

...6/-



Rajah 4(b)
Figure 4(b)

4. (a) Tentukan kekausalitan untuk sistem-sistem dengan sambutan dedenyut berikut:

Determine the causality for the systems with the following impulse responses.

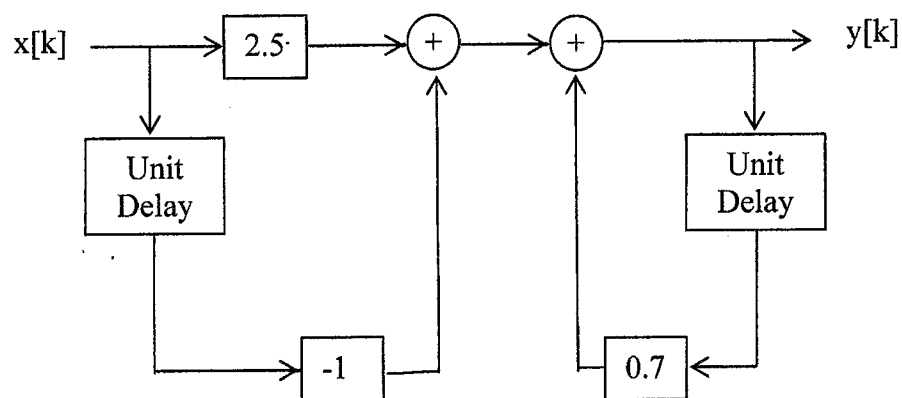
[i] $h[k] = k e^{-k} u[k]$

[ii] $h[k] = e^{-k} u[-k]$

(4%)

- (b) Pertimbangkan perwakilan gambarajah blok sistem dalam Rajah 5.

Consider the system block diagram representation of Figure 5.



Rajah 5
Figure 5

...7/-

- [i] Cari persamaan bezaan sistem ini.

Find the difference equation of the system.

(4%)

- [ii] Tentukan sambutan dedenyut $h[k]$, $0 \leq k \leq 4$ untuk sistem ini.

Determine the impulse response $h[k]$, $0 \leq k \leq 4$ for the system.

(5%)

- [iii] Katakan masukan sistem ini diberikan oleh

Suppose that the system input is given by

$$x[k] = \begin{cases} 1 & , \quad n = -2 \\ -3 & , \quad n = 0 \\ 2 & , \quad n = 1 \end{cases}$$

dan $x[k]$ ialah kosong untuk semua nilai k yang lain. Ungkapkan keluaran $y[k]$ sebagai fungsi $h[k]$.

and $x[k]$ is zero for all other values of k . Express the output $y[k]$ as a function of $h[k]$.

(7%)

5. (a) Pertimbangkan suatu sistem dengan masukan $x[k]$ dan keluaran $y[k]$ yang dispesifikasikan oleh persamaan.

Consider the system with an input $x[k]$ and output $y[k]$ specified by the equation.

$$y[k] = \sin\left(\frac{\pi k}{4}\right) x[k]$$

- [i] Adakah sistem ini lurus? Jelaskan jawapan anda.

Is this system linear? Justify your answer.

- [ii] Adakah sistem ini tak-ubah masa? Jelaskan jawapan anda.

Is this system time invariant? Justify your answer.

(10%)

- (b) Voltan pada nod ke- k suatu tangga berintangan dalam Rajah 6 ialah $v[k]$ ($k = 0, 1, 2, \dots, N$). Tunjukkan bahawa $v[k]$ memenuhi persamaan bezaan tertib- dua ini.

The voltage at the k th node of a resistive ladder in Figure 6 is $v[k]$. ($k = 0, 1, 2, \dots, N$). Show that $v[k]$ satisfies the second-order difference equation.

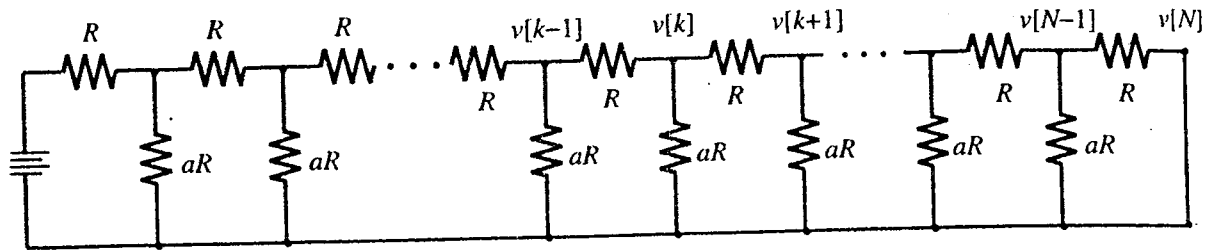
$$v[k+2] - A v[k+1] + v[k] = 0, \quad A = 2 + \frac{1}{a}$$

Panduan : Pertimbangkan persamaan nod pada nod ke- k dengan voltan $v[k]$.

Hint : Consider the node equation at the k th node with voltage $v[k]$.

(10%)

...9/-



Rajah 6
Figure 6

6. (a) Diberi jelmaan-z unilateral berikut:

Given the following unilateral z-transform:

$$X[z] = \frac{0.4 z^2}{(z-1)(z-0.6)}$$

- [i] Cari jelmaan-z songsang dengan kembangan pecahan separa.

Find the inverse z-transform by partial-fraction expansions.

(5%)

- [ii] Tentukan $x[k]$ untuk tiga nilai bukan kosong yang pertama dengan kembangkan $X[z]$ ke dalam suatu siri kuasa menggunakan pembahagian panjang.

Determine $x[k]$ for the first three nonzero values by expanding $X[z]$ into a power series using long division.

(5%)

...10/-

- (b) Pertimbangkan suatu sistem dengan masukan $x[k]$ yang diuraikan oleh persamaan bezaan berikut.

Consider a system with input $x[k]$ described by the following difference equation.

$$y[k] - 1.5 y[k-1] + 0.5 y[k-2] = x[k]$$

$$x[k] = \begin{cases} 1, & k = 1 \\ 0, & \text{otherwise} \end{cases}$$

Andaikan semua keadaan awal bernilai kosong.

Assume that all initial conditions are zero.

- [i] Cari fungsi pindah sistem.

Find the system transfer function.

(3%)

- [ii] Cari $y[k]$ menggunakan jelmaan-z.

Find $y[k]$, using the z-transform.

(3%)

- [iii] Guna ciri nilai terakhir untuk mengira $y[\infty]$. Adakah ciri nilai terakhir ini memberi nilai $y[\infty]$ yang betul?

Use the final-value property to evaluate $y[\infty]$. Is the final-value property give the correct value of $y[\infty]$?

(4%)

A Short Table of Fourier Transforms

$f(t)$	$F(\omega)$	
1 $e^{-at}u(t)$	$\frac{1}{a + j\omega}$	$a > 0$
2 $e^{at}u(-t)$	$\frac{1}{a - j\omega}$	$a > 0$
3 $e^{-a t }$	$\frac{2a}{a^2 + \omega^2}$	$a > 0$
4 $te^{-at}u(t)$	$\frac{1}{(a + j\omega)^2}$	$a > 0$
5 $t^n e^{-at}u(t)$	$\frac{n!}{(a + j\omega)^{n+1}}$	$a > 0$
6 $\delta(t)$	1	
7 1	$2\pi\delta(\omega)$	
8 $e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0)$	
9 $\cos \omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	
10 $\sin \omega_0 t$	$j\pi[\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$	
11 $u(t)$	$\pi\delta(\omega) + \frac{1}{j\omega}$	
12 $\text{sgn } t$	$\frac{2}{j\omega}$	
13 $\cos \omega_0 t u(t)$	$\frac{\pi}{2}[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)] + \frac{j\omega}{\omega_0^2 - \omega^2}$	
14 $\sin \omega_0 t u(t)$	$\frac{\pi}{2j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)] + \frac{\omega_0}{\omega_0^2 - \omega^2}$	
15 $e^{-at} \sin \omega_0 t u(t)$	$\frac{\omega_0}{(a + j\omega)^2 + \omega_0^2}$	$a > 0$
16 $e^{-at} \cos \omega_0 t u(t)$	$\frac{a + j\omega}{(a + j\omega)^2 + \omega_0^2}$	$a > 0$
17 $\text{rect}(\frac{t}{\tau})$	$\tau \text{sinc}(\frac{\omega\tau}{2})$	
18 $\frac{W}{\pi} \text{sinc}(Wt)$	$\text{rect}(\frac{\omega}{2W})$	
19 $\Delta(\frac{t}{\tau})$	$\frac{\tau}{2} \text{sinc}^2(\frac{\omega\tau}{4})$	
20 $\frac{W}{2\pi} \text{sinc}^2(\frac{Wt}{2})$	$\Delta(\frac{\omega}{2W})$	
21 $\sum_{n=-\infty}^{\infty} \delta(t - nT)$	$\omega_0 \sum_{n=-\infty}^{\infty} \delta(\omega - n\omega_0)$	$\omega_0 = \frac{2\pi}{T}$
22 $e^{-t^2/2\sigma^2}$	$\sigma\sqrt{2\pi}e^{-\sigma^2\omega^2/2}$	

Fourier Transform Operations

Operation	$f(t)$	$F(\omega)$
Addition	$f_1(t) + f_2(t)$	$F_1(\omega) + F_2(\omega)$
Scalar multiplication	$kf(t)$	$kF(\omega)$
Symmetry	$F(t)$	$2\pi f(-\omega)$
Scaling (a real)	$f(at)$	$\frac{1}{ a } F\left(\frac{\omega}{a}\right)$
Time shift	$f(t - t_0)$	$F(\omega)e^{-j\omega t_0}$
Frequency shift (ω_0 real)	$f(t)e^{j\omega_0 t}$	$F(\omega - \omega_0)$
Time convolution	$f_1(t) * f_2(t)$	$F_1(\omega)F_2(\omega)$
Frequency convolution	$f_1(t)f_2(t)$	$\frac{1}{2\pi} F_1(\omega) * F_2(\omega)$
Time differentiation	$\frac{d^n f}{dt^n}$	$(j\omega)^n F(\omega)$
Time integration	$\int_{-\infty}^t f(x) dx$	$\frac{F(\omega)}{j\omega} + \pi F(0)\delta(\omega)$

B.7 Miscellaneous

B.7-1 L'Hôpital's Rule

If $\lim f(x)/g(x)$ results in the indeterministic form $0/0$ or ∞/∞ , then

$$\lim \frac{f(x)}{g(x)} = \lim \frac{f'(x)}{g'(x)}$$

B.7-2 The Taylor and Maclaurin Series

$$f(x) = f(a) + \frac{(x-a)}{1!} f'(a) + \frac{(x-a)^2}{2!} f''(a) + \dots$$

$$f(x) = f(0) + \frac{x}{1!} f'(0) + \frac{x^2}{2!} f''(0) + \dots$$

B.7-3 Power Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!} + \dots$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \frac{x^8}{8!} - \dots$$

$$\tan x = x + \frac{x^3}{3} + \frac{2x^5}{15} + \frac{17x^7}{315} + \dots \quad x^2 < \pi^2/4$$

$$\tanh x = x - \frac{x^3}{3} + \frac{2x^5}{15} - \frac{17x^7}{315} + \dots \quad x^2 < \pi^2/4$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!} x^2 + \frac{n(n-1)(n-2)}{3!} x^3 + \dots + \binom{n}{k} x^k + \dots + x^n$$

$$\approx 1 + nx \quad |x| \ll 1$$

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + \dots \quad |x| < 1$$

B.7-4 Sums

$$\sum_{m=0}^k r^m = \frac{r^{k+1} - 1}{r - 1} \quad r \neq 1$$

$$\sum_{m=M}^N r^m = \frac{r^{N+1} - r^M}{r - 1} \quad r \neq 1$$

$$\sum_{m=0}^k \left(\frac{a}{b}\right)^m = \frac{a^{k+1} - b^{k+1}}{b^k(a - b)} \quad a \neq b$$

B.7-5 Complex Numbers

$$e^{\pm j\pi/2} = \pm j$$

$$e^{\pm jn\pi} = \begin{cases} 1 & n \text{ even} \\ -1 & n \text{ odd} \end{cases}$$

$$e^{\pm j\theta} = \cos \theta \pm j \sin \theta$$

$$a + jb = re^{j\theta} \quad r = \sqrt{a^2 + b^2}, \quad \theta = \tan^{-1} \left(\frac{b}{a} \right)$$

$$(re^{j\theta})^k = r^k e^{jk\theta}$$

$$(r_1 e^{j\theta_1})(r_2 e^{j\theta_2}) = r_1 r_2 e^{j(\theta_1 + \theta_2)}$$

B.7-6 Trigonometric Identities

$$e^{\pm jx} = \cos x \pm j \sin x$$

$$\cos x = \frac{1}{2}[e^{jx} + e^{-jx}]$$

$$\sin x = \frac{1}{2j}[e^{jx} - e^{-jx}]$$

$$\cos(x \pm \frac{\pi}{2}) = \mp \sin x$$

$$\sin(x \pm \frac{\pi}{2}) = \pm \cos x$$

$$2 \sin x \cos x = \sin 2x$$

$$\sin^2 x + \cos^2 x = 1$$

$$\cos^2 x - \sin^2 x = \cos 2x$$

$$\cos^2 x = \frac{1}{2}(1 + \cos 2x)$$

$$\sin^2 x = \frac{1}{2}(1 - \cos 2x)$$

$$\cos^3 x = \frac{1}{4}(3 \cos x + \cos 3x)$$

$$\sin^3 x = \frac{1}{4}(3 \sin x - \sin 3x)$$

$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y$$

$$\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$$

$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y}$$

$$\sin x \sin y = \frac{1}{2}[\cos(x - y) - \cos(x + y)]$$

$$\cos x \cos y = \frac{1}{2}[\cos(x - y) + \cos(x + y)]$$

$$\sin x \cos y = \frac{1}{2}[\sin(x - y) + \sin(x + y)]$$

$$a \cos x + b \sin x = C \cos(x + \theta)$$

$$\text{in which } C = \sqrt{a^2 + b^2} \quad \text{and} \quad \theta = \tan^{-1} \left(\frac{-b}{a} \right)$$

B.7-7 Indefinite Integrals

$$\int u dv = uv - \int v du$$

$$\int f(x)g'(x) dx = f(x)g(x) - \int f'(x)g(x) dx$$

$$\int \sin ax dx = -\frac{1}{a} \cos ax \qquad \int \cos ax dx = \frac{1}{a} \sin ax$$

$$\int \sin^2 ax dx = \frac{x}{2} - \frac{\sin 2ax}{4a} \qquad \int \cos^2 ax dx = \frac{x}{2} + \frac{\sin 2ax}{4a}$$

$$\int x \sin ax dx = \frac{1}{a^2} (\sin ax - ax \cos ax)$$

$$\int x \cos ax dx = \frac{1}{a^2} (\cos ax + ax \sin ax)$$

$$\int x^2 \sin ax dx = \frac{1}{a^3} (2ax \sin ax + 2 \cos ax - a^2 x^2 \cos ax)$$

$$\int x^2 \cos ax dx = \frac{1}{a^3} (2ax \cos ax - 2 \sin ax + a^2 x^2 \sin ax)$$

$$\int \sin ax \sin bx dx = \frac{\sin(a-b)x}{2(a-b)} - \frac{\sin(a+b)x}{2(a+b)} \qquad a^2 \neq b^2$$

$$\int \sin ax \cos bx dx = - \left[\frac{\cos(a-b)x}{2(a-b)} + \frac{\cos(a+b)x}{2(a+b)} \right] \qquad a^2 \neq b^2$$

$$\int \cos ax \cos bx dx = \frac{\sin(a-b)x}{2(a-b)} + \frac{\sin(a+b)x}{2(a+b)} \qquad a^2 \neq b^2$$

$$\int e^{ax} dx = \frac{1}{a} e^{ax}$$

$$\int x e^{ax} dx = \frac{e^{ax}}{a^2} (ax - 1)$$

$$\int x^2 e^{ax} dx = \frac{e^{ax}}{a^3} (a^2 x^2 - 2ax + 2)$$

$$\int e^{ax} \sin bx dx = \frac{e^{ax}}{a^2 + b^2} (a \sin bx - b \cos bx)$$

$$\int e^{ax} \cos bx dx = \frac{e^{ax}}{a^2 + b^2} (a \cos bx + b \sin bx)$$

$$\int \frac{1}{x^2 + a^2} dx = \frac{1}{a} \tan^{-1} \frac{x}{a}$$

$$\int \frac{x}{x^2 + a^2} dx = \frac{1}{2} \ln(x^2 + a^2)$$

B.7-8 Differentiation Table

$\frac{d}{dx} f(u) = \frac{d}{du} f(u) \frac{du}{dx}$	$\frac{d}{dx} a^{bx} = b(\ln a) a^{bx}$
$\frac{d}{dx} (uv) = u \frac{dv}{dx} + v \frac{du}{dx}$	$\frac{d}{dx} \sin ax = a \cos ax$
$\frac{d}{dx} \left(\frac{u}{v} \right) = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$	$\frac{d}{dx} \cos ax = -a \sin ax$
$\frac{dx^n}{dx} = nx^{n-1}$	$\frac{d}{dx} \tan ax = \frac{a}{\cos^2 ax}$
$\frac{d}{dx} \ln(ax) = \frac{1}{x}$	$\frac{d}{dx} (\sin^{-1} ax) = \frac{a}{\sqrt{1-a^2x^2}}$
$\frac{d}{dx} \log(ax) = \frac{\log e}{x}$	$\frac{d}{dx} (\cos^{-1} ax) = \frac{-a}{\sqrt{1-a^2x^2}}$
$\frac{d}{dx} e^{bx} = be^{bx}$	$\frac{d}{dx} (\tan^{-1} ax) = \frac{a}{1+a^2x^2}$

B.7-9 Some Useful Constants

$$\pi \approx 3.1415926535$$

$$e \approx 2.7182818284$$

$$\frac{1}{e} \approx 0.3678794411$$

$$\log_{10} 2 = 0.30103$$

$$\log_{10} 3 = 0.47712$$

B.7-10 Solution of Quadratic and Cubic Equations

Any quadratic equation can be reduced to the form

$$ax^2 + bx + c = 0$$

The solution of this equation is provided by

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

TABLE 2.1: Convolution Table

No	$f_1(t)$	$f_2(t)$	$f_1(t) * f_2(t) = f_2(t) * f_1(t)$
1	$f(t)$	$\delta(t - T)$	$f(t - T)$
2	$e^{\lambda t} u(t)$	$u(t)$	$\frac{1 - e^{\lambda t}}{-\lambda} u(t)$
3	$u(t)$	$u(t)$	$tu(t)$
4	$e^{\lambda_1 t} u(t)$	$e^{\lambda_2 t} u(t)$	$\frac{e^{\lambda_1 t} - e^{\lambda_2 t}}{\lambda_1 - \lambda_2} u(t) \quad \lambda_1 \neq \lambda_2$
5	$e^{\lambda t} u(t)$	$e^{\lambda t} u(t)$	$te^{\lambda t} u(t)$
6	$te^{\lambda t} u(t)$	$e^{\lambda t} u(t)$	$\frac{1}{2} t^2 e^{\lambda t} u(t)$
7	$t^n u(t)$	$e^{\lambda t} u(t)$	$\frac{n! e^{\lambda t}}{\lambda^{n+1}} u(t) - \sum_{j=0}^n \frac{n! t^{n-j}}{\lambda^{j+1} (n-j)!} u(t)$
8	$t^m u(t)$	$t^n u(t)$	$\frac{m! n!}{(m+n+1)!} t^{m+n+1} u(t)$
9	$te^{\lambda_1 t} u(t)$	$e^{\lambda_2 t} u(t)$	$\frac{e^{\lambda_2 t} - e^{\lambda_1 t} + (\lambda_1 - \lambda_2) te^{\lambda_1 t}}{(\lambda_1 - \lambda_2)^2} u(t)$
10	$t^m e^{\lambda_1 t} u(t)$	$t^n e^{\lambda_2 t} u(t)$	$\frac{m! n!}{(n+m+1)!} t^{m+n+1} e^{\lambda_1 t} u(t)$
11	$t^m e^{\lambda_1 t} u(t)$	$t^n e^{\lambda_2 t} u(t)$	$\sum_{j=0}^m \frac{(-1)^j m! (n+j)! t^{m-j} e^{\lambda_1 t}}{j! (m-j)! (\lambda_1 - \lambda_2)^{n+j+1}} u(t)$ $+ \sum_{k=0}^n \frac{(-1)^k n! (m+k)! t^{n-k} e^{\lambda_2 t}}{k! (n-k)! (\lambda_2 - \lambda_1)^{m+k+1}} u(t)$
	$\lambda_1 \neq \lambda_2$		
12	$e^{-\alpha t} \cos(\beta t + \theta) u(t)$	$e^{\lambda t} u(t)$	$\frac{\cos(\theta - \phi) e^{\lambda t} - e^{-\alpha t} \cos(\beta t + \theta - \phi)}{\sqrt{(\alpha + \lambda)^2 + \beta^2}} u(t)$ $\phi = \tan^{-1}[-\beta/(\alpha + \lambda)]$
13	$e^{\lambda_1 t} u(t)$	$e^{\lambda_2 t} u(-t)$	$\frac{e^{\lambda_1 t} u(t) + e^{\lambda_2 t} u(-t)}{\lambda_2 - \lambda_1} \quad \text{Re } \lambda_2 > \text{Re } \lambda_1$
14	$e^{\lambda_1 t} u(-t)$	$e^{\lambda_2 t} u(-t)$	$\frac{e^{\lambda_1 t} - e^{\lambda_2 t}}{\lambda_2 - \lambda_1} u(-t)$

TABLE 9.1: Convolution Sums

No.	$f_1[k]$	$f_2[k]$	$f_1[k] * f_2[k] = f_2[k] * f_1[k]$
1	$\delta[k - j]$	$f[k]$	$f[k - j]$
2	$\gamma^k u[k]$	$u[k]$	$\left[\frac{1 - \gamma^{k+1}}{1 - \gamma} \right] u[k]$
3	$u[k]$	$u[k]$	$(k + 1)u[k]$
4	$\gamma_1^k u[k]$	$\gamma_2^k u[k]$	$\left[\frac{\gamma_1^{k+1} - \gamma_2^{k+1}}{\gamma_1 - \gamma_2} \right] u[k] \quad \gamma_1 \neq \gamma_2$
5	$\gamma_1^k u[k]$	$\gamma_2^k u[-(k + 1)]$	$\frac{\gamma_1}{\gamma_2 - \gamma_1} \gamma_1^k u[k] + \frac{\gamma_2}{\gamma_2 - \gamma_1} \gamma_2^k u[-(k + 1)] \quad \gamma_2 > \gamma_1 $
6	$k \gamma_1^k u[k]$	$\gamma_2^k u[k]$	$\frac{\gamma_1 \gamma_2}{(\gamma_1 - \gamma_2)^2} \left[\gamma_2^k - \gamma_1^k + \frac{\gamma_1 - \gamma_2}{\gamma_2} k \gamma_1^k \right] u[k] \quad \gamma_1 \neq \gamma_2$
7	$ku[k]$	$ku[k]$	$\frac{1}{6} k(k - 1)(k + 1)u[k]$
8	$\gamma^k u[k]$	$\gamma^k u[k]$	$(k + 1)\gamma^k u[k]$
9	$\gamma^k u[k]$	$ku[k]$	$\left[\frac{\gamma(\gamma^k - 1) + k(1 - \gamma)}{(1 - \gamma)^2} \right] u[k]$
10	$ \gamma_1 ^k \cos(\beta k + \theta) u[k]$	$\gamma_2^k u[k]$	$\frac{1}{R} \left[\gamma_1 ^{k+1} \cos[\beta(k + 1) + \theta - \phi] - \gamma_2^{k+1} \cos(\theta - \phi) \right] u[k] \quad \gamma_2 \text{ real}$
			$R = \left[\gamma_1 ^2 + \gamma_2^2 - 2 \gamma_1 \gamma_2 \cos \beta \right]^{1/2}$
			$\phi = \tan^{-1} \left[\frac{(\gamma_1 \sin \beta)}{(\gamma_1 \cos \beta - \gamma_2)} \right]$

Table 11.1: (Unilateral) z-Transform Pairs

$f[k]$	$F[z]$
1 $\delta[k - j]$	z^{-j}
2 $u[k]$	$\frac{z}{z - 1}$
3 $ku[k]$	$\frac{z}{(z - 1)^2}$
4 $k^2u[k]$	$\frac{z(z + 1)}{(z - 1)^3}$
5 $k^3u[k]$	$\frac{z(z^2 + 4z + 1)}{(z - 1)^4}$
6 $\gamma^{k-1}u[k - 1]$	$\frac{1}{z - \gamma}$
7 $\gamma^k u[k]$	$\frac{z}{z - \gamma}$
8 $k\gamma^k u[k]$	$\frac{\gamma z}{(z - \gamma)^2}$
9 $k^2\gamma^k u[k]$	$\frac{\gamma z(z + \gamma)}{(z - \gamma)^3}$
10 $\frac{k(k-1)(k-2)\cdots(k-m+1)}{\gamma^m m!} \gamma^k u[k]$	$\frac{z}{(z - \gamma)^{m+1}}$
11a $ \gamma ^k \cos \beta k u[k]$	$\frac{z(z - \gamma \cos \beta)}{z^2 - (2 \gamma \cos \beta)z + \gamma ^2}$
11b $ \gamma ^k \sin \beta k u[k]$	$\frac{z \gamma \sin \beta}{z^2 - (2 \gamma \cos \beta)z + \gamma ^2}$
12a $r \gamma ^k \cos(\beta k + \theta)u[k]$	$\frac{rz[z \cos \theta - \gamma \cos(\beta - \theta)]}{z^2 - (2 \gamma \cos \beta)z + \gamma ^2}$
12b $r \gamma ^k \cos(\beta k + \theta)u[k]$	$\gamma = \gamma e^{j\beta} \quad \frac{(0.5re^{j\theta})z}{z - \gamma} + \frac{(0.5re^{-j\theta})z}{z - \gamma^*}$
12c $r \gamma ^k \cos(\beta k + \theta)u[k]$	$\frac{z(Az + B)}{z^2 + 2az + \gamma ^2}$
$r = \sqrt{\frac{A^2 \gamma ^2 + B^2 - 2AaB}{ \gamma ^2 - a^2}}$ $\beta = \cos^{-1} \frac{-a}{ \gamma }, \quad \theta = \tan^{-1} \frac{Aa - B}{A\sqrt{ \gamma ^2 - a^2}}$	

Table 11.2
Z- Transform Operations

Operation	$f[k]$	$F[z]$
Addition	$f_1[k] + f_2[k]$	$F_1[z] + F_2[z]$
Scalar multiplication	$af[k]$	$aF[z]$
Right-shift	$f[k-m]u[k-m]$	$\frac{1}{z^m}F[z]$
	$f[k-m]u[k]$	$\frac{1}{z^m}F[z] + \frac{1}{z^m} \sum_{k=1}^m f[-k]z^k$
	$f[k-1]u[k]$	$\frac{1}{z}F[z] + f[-1]$
	$f[k-2]u[k]$	$\frac{1}{z^2}F[z] + \frac{1}{z}f[-1] + f[-2]$
	$f[k-3]u[k]$	$\frac{1}{z^3}F[z] + \frac{1}{z^2}f[-1] + \frac{1}{z}f[-2] + f[-3]$
Left-shift	$f[k+m]u[k]$	$z^mF[z] - z^m \sum_{k=0}^{m-1} f[k]z^{-k}$
	$f[k+1]u[k]$	$zF[z] - zf[0]$
	$f[k+2]u[k]$	$z^2F[z] - z^2f[0] - zf[1]$
	$f[k+3]u[k]$	$z^3F[z] - z^3f[0] - z^2f[1] - zf[2]$
Multiplication by γ^k	$\gamma^k f[k]u[k]$	$F\left[\frac{z}{\gamma}\right]$
Multiplication by k	$kf[k]u[k]$	$-z \frac{d}{dz}F[z]$
Time Convolution	$f_1[k] * f_2[k]$	$F_1[z]F_2[z]$
Frequency Convolution	$f_1[k]f_2[k]$	$\frac{1}{2\pi j} \oint F_1[u]F_2\left[\frac{z}{u}\right] u^{-1} du$
Initial value	$f[0]$	$\lim_{z \rightarrow \infty} F[z]$
Final value	$\lim_{N \rightarrow \infty} f[N]$	$\lim_{z \rightarrow 1} (z-1)F[z]$ poles of $(z-1)F[z]$ inside the unit circle.